Kinematic Analysis of Crank Shaft for Diesel Engine

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Abstract: As the crankshaft is subjected to complex bending shear and twisting loads, it needs to be well designed and manufactured in good quality material to withstand the stress. As these stresses may change in direction and magnitude as the crankshaft rotates. In the balancing of the crankshaft, it needs to consider both the static balancing and dynamic balancing. In design calculation of crankshaft kinematics of crank gear, indicator diagram, force acting on the crankshaft and torque acting to the major journal and crank pin are important. The influence of the forces due to inertia both the reciprocating and rotating masses must be taken into account as accurately as possible, especially for high speed. The engine is four cylinders, four-stroke engine, and compression ratio is 20. The maximum power output of the shaft is 70.4 kW at 3200 rpm. The crankpin diameter and length are 56 mm and 31 mm, the main journal diameter and length are 65 mm and 32 mm. The operating conditions of cranks gear elements characterized by the forces which appear in them at various engine duties.

Keywords: velocity, gas pressure, inertia force and net force

1. INTRODUCTION

The crankshaft serves as the main rotating members, or shaft of the engines. The main function of the crank shaft is charging reciprocating motion to rotary motion. The crankshaft has offset journals to which the connecting rods are attached; it converts their up and down motion into rotary motion. It withstands bending stresses and torsional stresses during the whole time of operation. The connecting rod is connected to the piston by piston pin and to the crankshaft by the crankpin the output end of the crankshaft has flywheel. The front end has the gear or sprocket that drives the crankshaft, the vibration damper and the drives-belt pulley. Central crank gear is as shown Figure 1.

2. KINEMATIC of CRANK GEAR

The operation condition of the crank gear element are characterized by the forces which appear in them at various engine duties. The magnitude and the nature of the change of the mechanical loads taken by these elements are determined from kinematic and dynamic investigations of the crank gear. In many modern engine are piston pin axis is offset by 0.01 to 0.03 of its diameter from the cylinder axis in order to achieve continuous elimination of the clearance between the piston and the cylinder wall and the more favorable distribution of load on the piston wall. The ratio between the crank radius and the connecting rod length is assigned.

$$\lambda = \frac{R}{Load}$$
(1)
k = $\frac{a}{2}$ (2)

$$k = \frac{a}{R}$$
 (
The niston travel can be calculated

$$s=R\left[(1-\cos\phi)+\frac{\lambda}{4}(1-\cos2\phi)-k\lambda\sin\phi\right]$$
(3)

The piston velocity can be calculated

$$V_{\rm p} = R\omega \left(\sin \phi + \frac{\lambda}{2} \sin 2\phi - k\lambda \cos \phi \right)$$
(4)

The acceleration of the piston is

$$A = R (\cos \Phi + \lambda \cos 2\Phi + k\lambda \sin \Phi)$$
(5)

where,

 $\mathbf{R} = \operatorname{crank} \operatorname{radius}$

 $\lambda =$ dimensionless parameters

 $\mathbf{k} = \mathbf{the\ relative\ displacement}$

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a = displacement of the plane of travel of the piston pin axis from crankshaft axis



Figure 1.The offset engine crank gear

 Φ = angle of crank travel counted from the cylinder axis in the direction of clockwise crankshaft rotation

 β = angle between the connecting rod and cylinder axis

 ω = angular velocity of crankshaft rotation

S = 2R = piston stroke

 $L_{Rod} = connecting rod length$

 $V_p = piston velocity$

A = acceleration of the piston

Take the rotational speed of engine N = 3200 rpm and the offset is 0.015D [2]. Piston-travel, velocity and acceleration with corresponding crank angle are shown in Table 1.

Degree	Piston travel	Velocity	Acceleration
0	0	-0.130	6715.190
30	7.69	9.9597	5270.161
60	27.8379	15.287	1845.7815
90	52.511	15.415	-1505.959
120	73.837	11.413	-3319.750
150	87.367	5.818	-3676.801
180	92	0.130	-3615.872
210	87.756	-5.592	-3720.440
240	74.369	-11.2821	-3395.44
270	53.289	-15.415	-1593.359
300	28.512	-15.417	1770.090
330	8.082	-9.822	5226.460
360	0	-0.130	6715.190

Table 1. Piston travel, velocity, acceleration with corresponding crank angle

2.1 Indicator Diagram

On the volume line, A piece of line AB corresponding to swept volume of cylinder. Then the volume which corresponding to the volume of combustion chamber is determine

$\mathbf{v} = \mathbf{AB}$	
$V_c = \frac{1}{r^{c-1}}$	(6)
$\tan \beta_1 = (1 + \tan \alpha)^{n1} - 1$	(7)
$\tan \beta_1 = (1 + \tan \alpha)^{n^2} - 1$	(8)

 $\tan \beta_1 = (1 + \tan \alpha)^{n^2} - 1$

where

n₁ and n₂ are polytropic exponents of compression and expansion respectively

where.

 V_c = clearance volume

From Figure 2 , construct a table , which express the relationship of the crank angle and the gas pressure in the step up of 30 can be calculated. The developed indicated diagram is shown in followed.

2.2 Force acting on a crankshaft

The forces on the crank gear are divided into the force of gas pressure in the cylinder, the forces of inertia of the moving parts in the mechanism, and the inertia and centrifugal forces of the rotating parts. The gas pressure forces are the principal forces at low engine speeds, but the inertia force may be considerably larger at high speeds. The centrifugal force also increases rapidly with an increase in speed. The pressure of gas in the engine cylinder creates the force applied to the cylinder head. This force is directed along the cylinder axis and it is equal in magnitude and opposite in direction to the force acting on the piston. The force of gas pressure in the cylinder is determine by (9)

 $P_G = (P_g - P_o). A_p$

where .

 P_G = force of the gas pressure

A_p = area of the piston



Figure 2. Indicator Diagram for vertical axis is pressure and horizontal axis is piston stroke.

Table 2. Gas pressure of various crank angles

Degree	Gas Pressure(kg/cm ²)
0	1.133
30	0.97275
60	0.86055
90	0.6908
120	0.7055
150	0.8819
180	0.9001
210	0.9259
240	1.204425
270	1.87517
300	3.35702
330	12.38406
360	65.7187

2.3 Inertia force

To determine the force of inertia, it is necessary to know the masses of crank gear elements. To simplify the calculations, the actual crank gear is replaced by a dynamically equivalent system of lumped masses. All the moving parts are divided into the groups with respect to the nature of their motion. They are,

(i) Parts reciprocating along the cylinder axis (piston group)

The mass of piston with piston rings assumed to be assumed to be lumped on the piston pin axis and is designated by, mp.

Rotating parts of the crankshaft (ii)

Their mass are replaced by a mass reduced to the crank radius R and are designated by m_R. This reduction is so performed as to ensure quality between the centrifugal force of inertia of the actual masses and that of reduced mass.

The mass of the crank pin m_{cp} with adjacent parts of the webs(a is assumed to be lumped along the center of the crank pin axis and, since its center of the gravity is at a distance R from the shaft axis, this must need not be reduced.



Figure 3. Reduction of the crank gear system to a two-mass one.[1]

The mass m_{cw} of the middle portion of the crank web over the countour "abcd" with its center of gravity on the radius is reduced to the radius R.

 $m_{cw}R_1\omega^2 = (m_{cw})_R R \omega^2$ (10)

$$(\mathbf{m}_{cw})_{\mathbf{R}} = \mathbf{m}_{cw} \mathbf{R}_{1} / \mathbf{R} \tag{11}$$

Therefore the reduced mass of the crank is,

$$m_{cr} = m_{cp} + 2(m_{cw})R = m_{cp} + 2 m_{cw}R_1/R$$
 (12)

(iii) Parts performing complex plane-parallel motion space (connecting rod group). The connecting rod is replaced with a certain approximation by a system of two masses statically equivalent to its mass-the mass $m_{rod,pp}$ lumped on the piston pin axis, and the mass $m_{rod,cr}$ the axis of the crankpin. For this purpose, the mass of the connecting rod m_{rod} is divided into two masses that referred to the piston pin axis.

$$m_{\rm rod,pp} = m_{\rm rod} L_{\rm rodcr} / L_{\rm rod}$$
(13)

(14)

and, that referred to the crank axis, $m_{rod.cr} = m_{rod} L_{rodpp} / L_{rod}$

According to the statistical data, for most design of engine,

$$m_{rod.pp} = (0.2 \text{ to } 0.3) m_{rod}$$

 $m_{rod.cr} = (0.7 \text{ to } 0.8) m_{rod}$

Thus, the entire crank gear is replaced by a system of two lumped masses connected by rigid weight less linksthe reciprocating mass at point A,

$$m_1 = m_p + m_{rod,pp}$$
 (15)
where $m_{rod,pr} = mass of connecting rod referred to$

 $m_R = m_{cr} + m_{rod,cr}$ (16) where, $m_{rod,cr} = mass$ of connecting rod referred to

crank pin. The value of m_{pp} and m_{rod} are selected according to data of available designs. The design masses of crank gear elements referred to one unit area of piston A_p are given in Table.

Table 3.Design Masses of Crank Gear Elements(g/cm²)

Type of Engine	Mass of Piston	Mass of
	from aluminum	connecting rod
	alloy m _p "	m _{rod} "
Carburetor	10-15	12-20
engines(D= 60 to		
100mm)		
Diesel engines	20-30	25-35
(D = 80 to 120 mm)		

The mass of piston group,

$$\mathbf{m}_{\mathbf{p}} = \mathbf{m}_{\mathbf{p}}^{"} \times \mathbf{A}_{\mathbf{p}} \tag{17}$$

The mass of connecting rod

$$m_{rod} = m_{rod} \times A_p$$
 (18)

 $m_{rod} = m_{rod} \times A_p$ where , $m_p = mass$ of piston

 $m_{rod} = mass of connecting rod$

According to the statistical data, for most design of engine

$$m_{rod pp} = (0.2 \cdot 0.3) m_{rod}$$
(19)
$$m_{rod cr} = (0.7 \cdot 0.8) m_{rod}$$
(20)

The entire crank gear is replaced by a system of two lumped masses connected by rigid weightless links the reciprocating mass at point A,

$$\mathbf{m}_{1} = \mathbf{m}_{p} + \mathbf{m}_{rod \ pp} \tag{21}$$

Force of inertia (F_i) included by reciprocating mass is determined.

$$F_{i} = -m_{i} R \omega^{2} (\cos \Phi + \lambda \cos 2\Phi + k \lambda \sin \Phi)$$
(22)
The rotating mass at pt B

 $m_{\rm R} = m_{\rm cr} + m_{\rm rod \ cr} \tag{23}$

The gas pressure force and the inertia force may be combined algebraically to determine the net force acting along the cylinder axis. Force acting toward the crank shaft are plotted as positive values. Thus ,only the induction and the first part of the compression stroke will have negative value. The inertia forces are always negative at the top and positive at the bottom of the stroke. The net force acting along the cylinder axis can be determined by $F = P_C + F_c$ (24)

 $F = P_G \pm F_i$ (24) At various crank angle Φ , the gas pressure force P_G , the inertia force F_i and the net force F are change or various with their corresponding crank angle and presented in Table 3.

Table 4.Gas pressure force of various crank angle

Deemaa A	Gas Pressure	Inertia	Net Force,F
Degree, φ	Force, P _G , kg	Force,F _I , kg	kg
0	7.591	-1056.098	-1048.506
30	-1.1829	-828.833	-830.017
60	-7.959	-290.643	-298.602
90	-17.648	236.842	219.194
120	-16.809	522.097	505.288
150	-6.741	578.251	571.51
180	-5.702	568.668	562.966
210	-4.229	585.159	580.93
240	11.668	533.736	545.404
270	49.953	250.539	300.492
300	134.536	-278.404	-143.868
330	649.790	-821.887	172.097
360	3694.078	-1356.098	2637.98

2.4 Piston side thrust and connecting rod force

The net force is exerted in the direction along the cylinder axis. The angularity of the connecting rod causes the net force to be divided into two components; one producing piston thrust against the cylinder wall, and the other acting along the axis of the connecting rod.

The piston side thrust against the cylinder wall determined by $Q = F \tan \beta = F \lambda (\sin \Phi - k)$ (25)

The force along the connecting rod is determined by

$$K = \frac{F}{\cos\beta} = F \left[1 + \frac{\lambda^2}{4} \left(1 - \cos 2\varphi \right) \right]$$
(26)

The tangential force at the crank pin is determined by the resolving the force along the connecting rod into two components, one acting tangentially to the crank circle at the crank pin and the other acting radially at the crank pin. The tangential force to the crank radius circle and normal force directed along the crank radius are

$$F_{t} = F\left(\sin\phi + \frac{\lambda}{2}\sin2\phi \cdot k\lambda\cos\phi\right)$$
(27)

$$N=F\left(\cos\phi - \frac{\lambda}{2}\left(1 - \cos 2\phi\right) + k\lambda \sin\phi\right)$$
(28)

A couple of force appears with a moment, T called the torque and is determined

$$T = F_t \times R \tag{29}$$

Table 5. Th	e relation	of the	force Q,	k, F _t	and N
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Degree	Side Thrust Force	Force	Tangential Force	Normal Force
0	8.870	-1048.5	8.87	-1048.50
30	-117.48	-839.35	-516.75	-660.07
60	-75.05	-308.68	-296.12	-84.29
90	63.90	229.06	219.19	-63.9
120	127.00	522.34	373.91	-362.59
150	80.89	577.94	215.69	-535.39
180	-4.76	562.06	4.76	-562.96
210	-92.05	587.46	-210.70	-549.15
240	-146.31	563.81	-399.18	-399.40
270	-92.69	314.01	-300.49	-92.69
300	38.59	-148.72	143.89	-38.50
330	27.27	-174.03	109.66	-135.40
360	-22.32	2637.98	-22.32	2637.98

The relation of the force Q, k, F_t and N are shown in Table 3. The torque on the main journals V_s the torque of the crank pin for four cylinders four-stroke engine are shown following.

Table 6. Within the crank angle of Torque

Degree	Torque	Degree	Torque
0	0.40802	390	24.532
30	-23.770	420	2.699
60	-13.622	450	19.091
90	10.084	480	23.459
120	17.199	510	12.935
150	9.922	540	0.278
180	0.219	570	-10.105
210	-9.692	600	-18.164
240	-18.362	630	-11.589
270	-13.822	660	13.042
300	6.618	690	24.195
330	5.044	720	0.40802
360	-1.026		

Using the data of table 5, plotted the torque on the main journals and the torque on the crank pin for a four cylinder four stroke engine is plotted. Shown in followed.



Figure 4. Accumulating torque diagram of main journal for diesel engine



Figure 5. Accumulating torque diagram of crank pin for diesel engine.

3. CONCLUSION

In this paper, the author used the double span crankshaft. In the indicated diagram calculation taken the assumed valued i.e the polytropic exponent of compression n_1 is between the range of 1.32 to 1.4 and taken as 1.32 and polytropic exponent of expansion n_2 is 1.18 to 1.28 and taken as 1.18. The mean piston speed is within the range of 5 to 9 and taken as 7 m/s. This crankshaft design is specially design for high speed light vehicles. Not only this design is economy from commercial point of view but also it can be used for prolonged time.

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